The VLX-60 is a member of the VLX series of Electric Encoders™: a product line based on Netzer Precision Motion Sensor proprietary technology. EE products are characterized by features that enable unparalleled performance:

- Low profile (<10 mm)

- Hollow shaft (Stator / Rotor)

- No bearings or other contact elements

- High resolution and unparalleled precision

- High tolerance to temperature extremes, shock, moisture, EMI, RFI and magnetic fields

- Very low weight

- Holistic signal generation

- Digital interfaces for absolute position

The holistic structure of the Electric Encoder™ makes it unique: Its output reading is the averaged outcome of the entire area of the rotor. This feature allows the EE a tolerant mechanical mounting and to deliver outstanding precision.

Due to the absence of components such as ball bearings, flexible couplers, glass discs, light sources and detectors along with very low power consumption enables the EE to deliver virtually failure-free performance in nearly all types of conditions.

The internally shielded, DC- operated EE includes an electric field generator, a field receiver, sinusoidal-shaped dielectric rotor, and processing electronics.

The EE output is a digital serial synchronous with absolute position single turn.

This combination of high precision, low profile and, low weight has made Netzer Precision encoders highly reliable and particularly well suited to a wide variety of industrial automation applications.

General

Angular resolution	18-20 bit
Maximum tested static error	≤ 0.015°
Extended accuracy static error	≤ 0.010°
Maximum operational speed	4,000 rpm
Measurement range	Single turn, unlimited
Rotation direction	Adjustable CW/CCW*

* Default same direction from bottom side of the encoder

Mechanical

Allowable mounting eccentricity	±0.1 mm
Allowable rotor axial motion	±0.1 mm
Rotor inertia	1,930 gr · mm^2
Total weight	14
Outer Ø /Inner Ø/ Height	60 / 25/ 8 mm
Material (stator, rotor)	FR4
Nominal air gap (stator, rotor)	0.6 mm

Electrical

Supply voltage	5V ± 5%
Current consumption	90 mA
Interconnection	Connector

Environmental

EMC	IEC 6100-6-2, IEC 6100-6-4
Operating temperature	-25°C to +65°C
Storage temperature	-40°C to +100°C
Relative humidity	98% Non condensing
Shock endurance	100 g for 11 ms
Vibration endurance	20 g 10 – 2000 Hz
Protection	IP 40

Calibration / Compensation

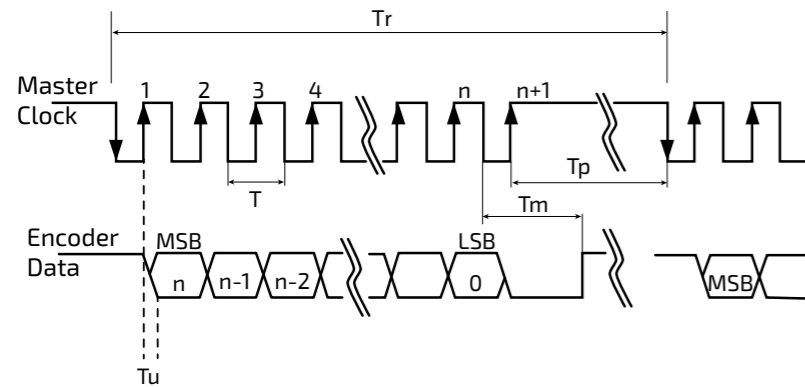|	
Offsets	Automatic / Manual
Signals level	Automatic / Manual
Signals integrity	Error / Warning report
Thermal	Error / Warning report
Zero position	Manual
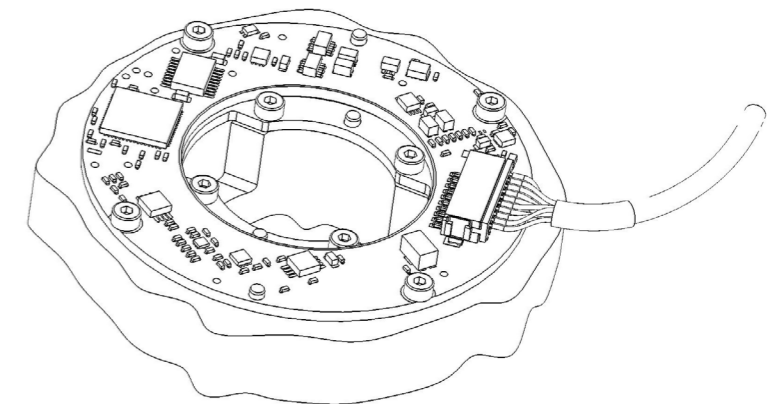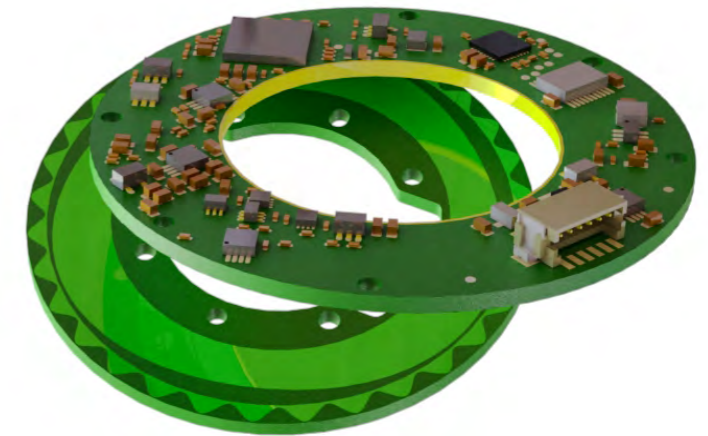
Digital SSi Interface

Synchronous Serial Interface (**SSI**) is a point to point serial interface standard between a master (e.g. controller) and a slave (e.g. sensor) for digital data transmission.

Description		Recommendations
n	Total number of data bits	12 - 22
T	Clock period	
f= 1/T	Clock frequency	0.1 - 5.0 MHz
Tu	Bit update time	90 nsec
Tp	Pause time	26 - ∞ µsec
Tm	Monoflop time	>25 µsec
Tr	Time between 2 adjacent requests	Tr > n*T+26 µsec
fr=1/Tr	Data request frequency	
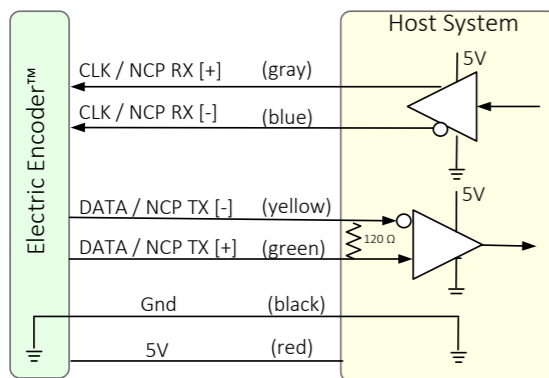
SSi / BiSS output signal parameters

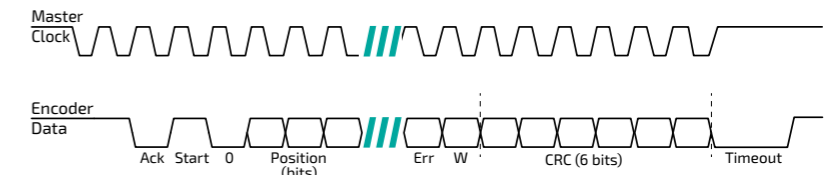| Output code	Binary
Serial output	Differential RS-422
Clock	Differential RS-422
Clock Frequency	0.1 ÷ 5.0 MHz
Position update rate	35 kHz (Optional - up to 375 KHz)

SSi/BiSS interface pin/cable color code

DF-13 on-board connector pin#	DB9 F (cable end) pin#	Cable Color	Function
7	1	Blue	CLK - / NCP RX -
8	2	Gray	CLK + / NCP RX +
5	3	Green	DATA + / NCP TX +
6	4	Yellow	DATA - / NCP TX -
4	5	Black	GND
3	8	Red	5v

Software tools: (SSi / BiSS - C)

Advanced calibration and monitoring options are available by using the factory supplied Electric Encoder Explorer software, This facilitates proper mechanical mounting, offsets calibration and advanced signal monitoring.
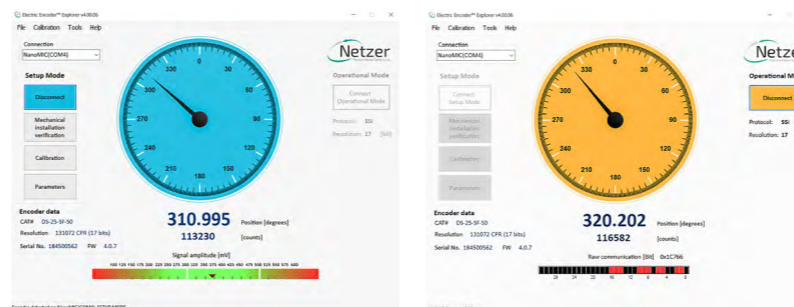

Digital BiSS-C Interface

BiSS – C Interface is unidirectional serial synchronous protocol for digital data transmission where the Encoder acts as "slave" transmits data according to "Master" clock. The BiSS protocol is designed in B mode and C mode (continuous mode) .The BiSS-C interface as the SSi is based on RS-422 standards.

Bit #		Description	Default	Length
28	Ack	Period during which the encoder calculates the absolute position, one clock cycle	0	1/clock
27	Start	Encoder signal for "start" data transmit	1	1 bit
26	"0"	"start" bit follower	0	1 bit
8...25	AP	Absolute Position encoder data		
7	Error	Error (BIT Optional)	1	1 bit
6	Warn.	Warning (non active)	1	1 bit
0...5	CRC	The CRC polynomial for position, error and warning data is: x6 + x1 + x0. It is transmitted MSB first and inverted. The start bit and "0" bit are omitted from the CRC calculation.		6 bits
	Timeout	Elapse between the sequential "start"request cycle's.		25 µs

Netzer
Precision Motion Sensors

ABSOLUTE POSITION
ROTARY ELECTRIC ENCODER™

INDUSTRIAL AUTOMATION | VLX-60 Qcore

DATA SHEET

Ordering Code

VLX - 60 - S H - C H

VLX	Product line

Outer Diameter

Output	
S	SSi
I	BiSS

Resolution		
Code	Bit	CPR
G	18	262,144
H	19 [1]	524,288
I	20	1,048,576

Notes	
1	Resolution - optional, call

Interconnection	
H	Connector - Horizontal
V	Connector - Vertical
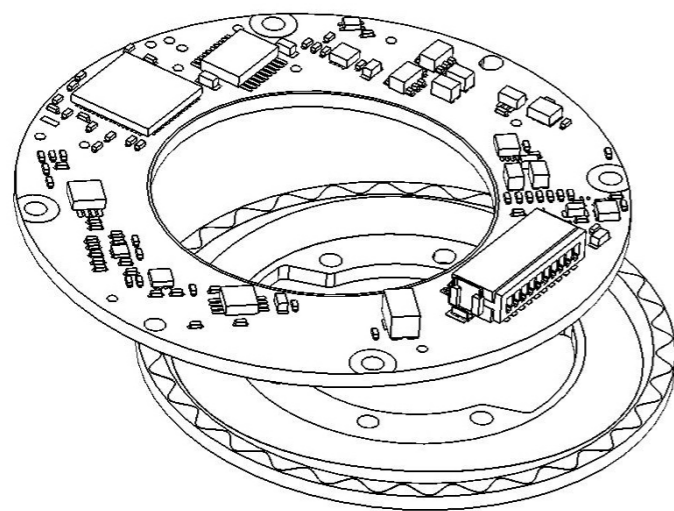
Optional Accessories

Accessories - cables, optional

SSi / BiSS	Remarks
CB-00088-250	AWG30, 250 mm
CB-00088-500	AWG30, 500 mm

Netzer Cat No.: CB 00014
Provider: Ray-Q USA. CAT No.: RQ 213210
Cable: 30 AWG twisted pair (3): 2 (30 AWG 25/44 tinned copper,
Insulation: PFE Ø 0.15 to Ø 0.6 ± 0.05 OD).
Temperature rating: -60 to +150 Deg C.
Braided shield: Thinned copper braided 95% min. coverage.
Jacket: 0.44 silicon rubber (NFA 11-A1) Ø3.45 ±0.2 OD

Pair#	Color
A1-A2	Red / Black
A3-A4	Gray / Blue
A5-A6	Green / Yellow

30 AWG twisted pairs (3)
Braided shield
Jacket 0.44mm
Ø 3.45 ±0.2 mm

0.017
30 AWG single insulated wire
Ø 0.61 ± 0.051mm
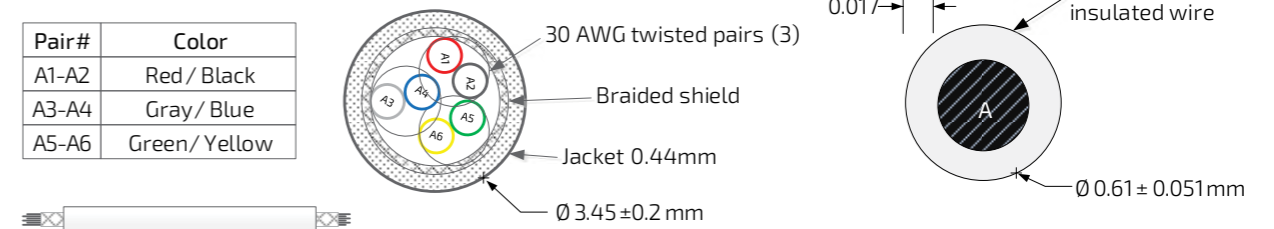
Related documents

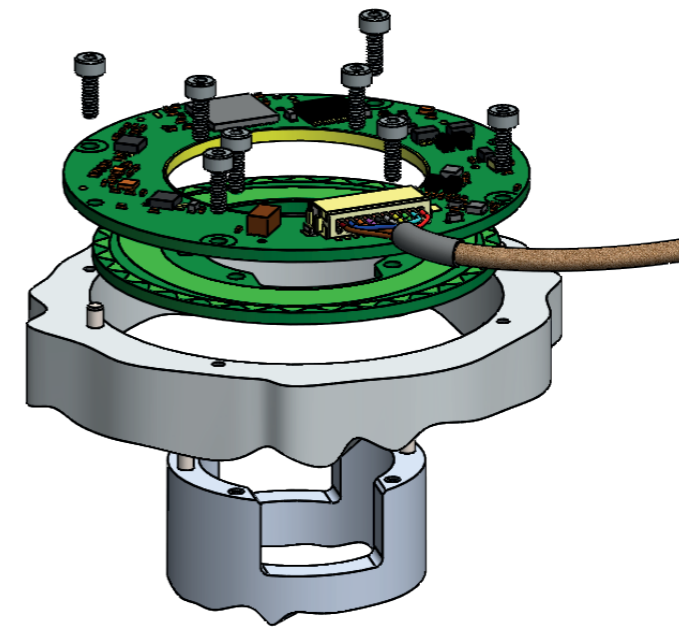LX-60 User Manual: Mechanical , Electrical and calibration setup.
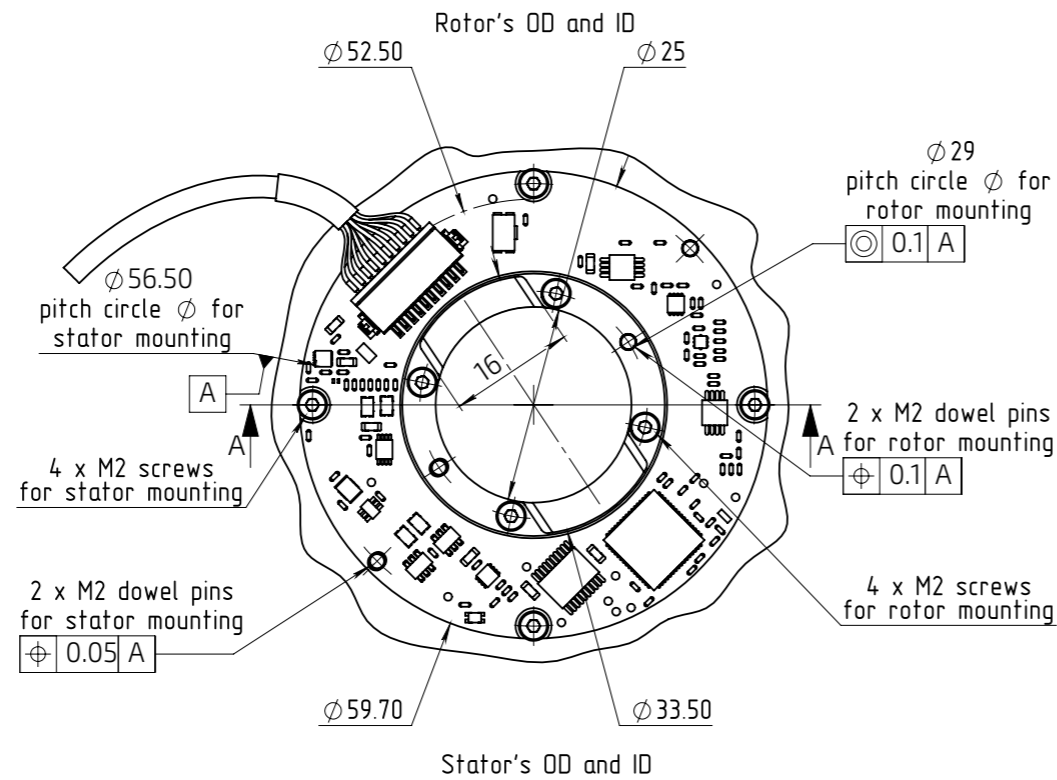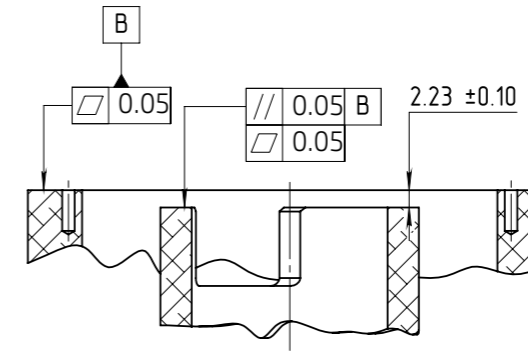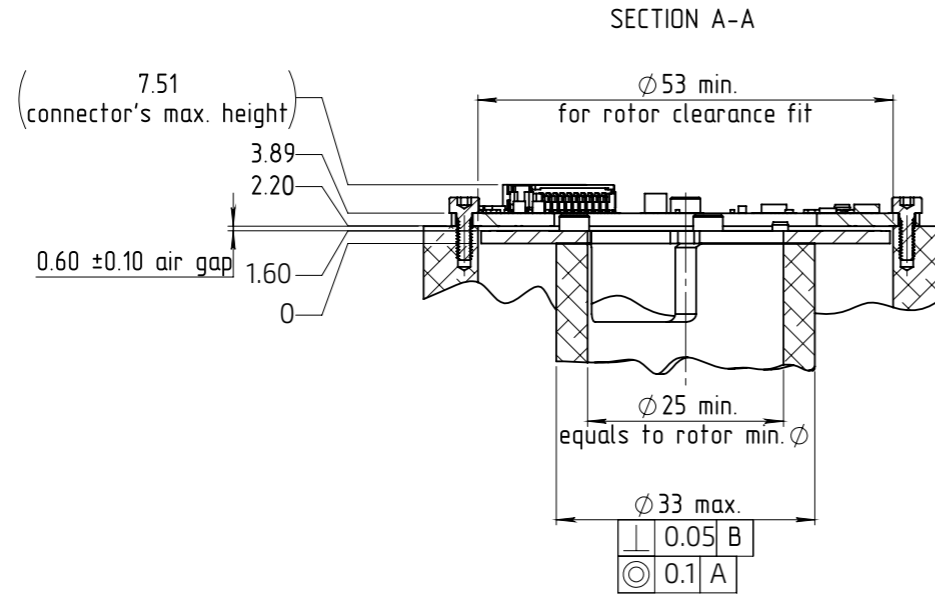
Demonstration Kit

DKIT-VLX-60-SG with SSi interface
DKIT-VLX-60-IG withe BiSS interface Includes, mounted encoder on rotary jig, and RS-422 to USB converter.

Sold & Serviced By:

Canadian and International Sales
ELECTROMATE
877-737-8698
sales@electromate.com
www.electromate.com

U.S. Sales
SERVO2GO.com
877-378-0240
sales@servo2go.com
www.servo2go.com

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ABSOLUTE POSITION
ROTARY ELECTRIC ENCODER™

INDUSTRIAL
AUTOMATION | VLX-60 Qcore

DATA SHEET

SECTION A-A

7.51
(connector's max. height)

3.89
2.20

0.60 ±0.10 air gap

1.60

0

$\varnothing$ 53 min.
for rotor clearance fit

$\varnothing$ 25 min.
equals to rotor min. $\varnothing$

$\varnothing$ 33 max.

| ⊥ | 0.05 | B |
| ◎ | 0.1 | A |

B

| ▱ | 0.05 |

| // | 0.05 | B |
| ▱ | 0.05 |

2.23 ±0.10

SECTION B-B

Rotor's OD and ID

$\varnothing$ 52.50

$\varnothing$ 25

$\varnothing$ 29
pitch circle $\varnothing$ for
rotor mounting

| ◎ | 0.1 | A |

$\varnothing$ 56.50
pitch circle $\varnothing$ for
stator mounting

A

4 x M2 screws
for stator mounting

16

A
A

2 x M2 dowel pins
for rotor mounting

| ⊕ | 0.1 | A |

2 x M2 dowel pins
for stator mounting

| ⊕ | 0.05 | A |

4 x M2 screws
for rotor mounting

$\varnothing$ 59.70

$\varnothing$ 33.50

Stator's OD and ID

Unless otherwise specified
Dimensions are in: mm
Surface finish: N6
Linear tolerances: ±0.1 deg